

# On full linear convergence and optimal complexity of adaptive FEM with inexact solver

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joint work with M. Brunner, M. Feischl, A. Miraçi, D. Praetorius, J. Streitberger



slides

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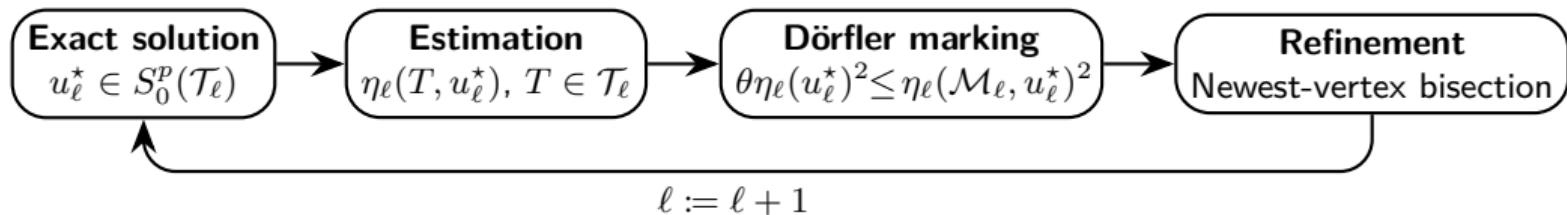
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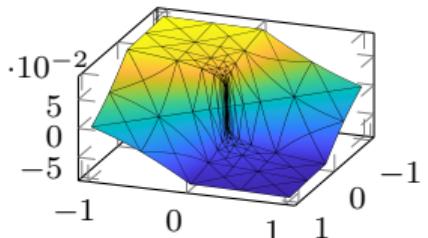
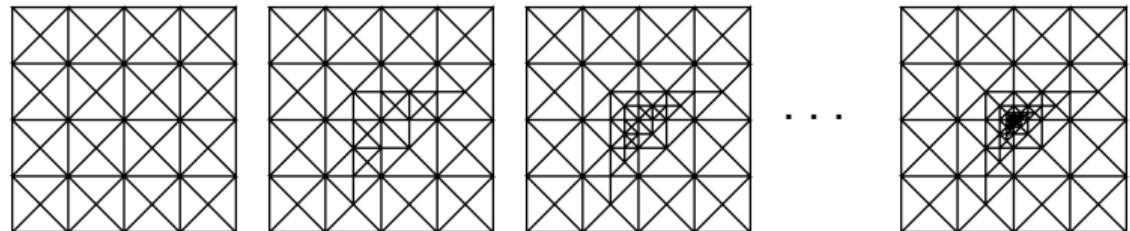


# Standard AFEM algorithm

**Input:** initial triangulation  $\mathcal{T}_0$ , adaptivity parameter  $0 < \theta \leq 1$



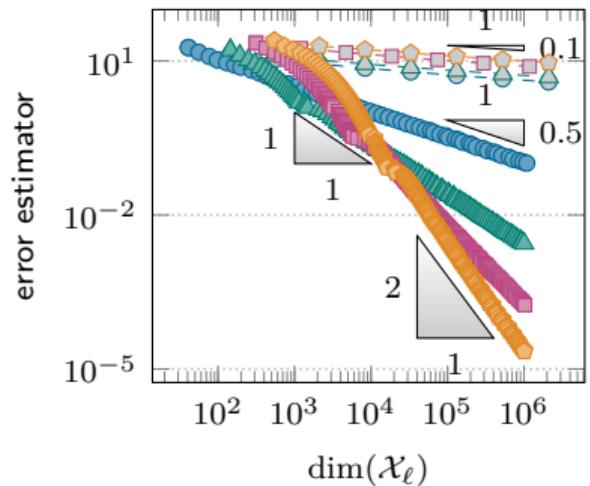
**Output:** triangulations  $\mathcal{T}_\ell$  with corresponding discrete solution  $u_\ell^*$  and estimators  $\eta_\ell(u_\ell^*)$



Kellogg: *Applicable Anal.*, 4 (1974)

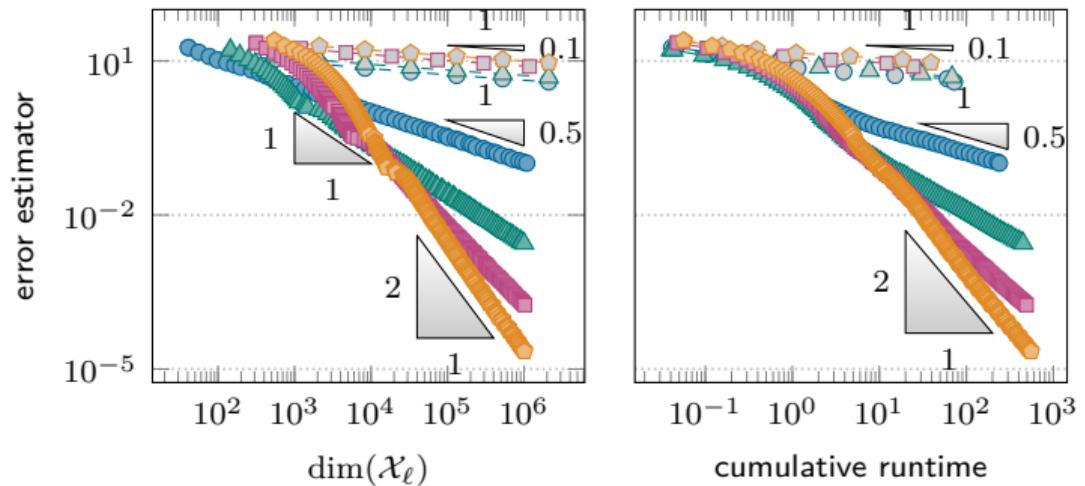
Bringmann, Miraçi and Praetorius: arXiv: 2404.07126 (2024)

# How to measure convergence?



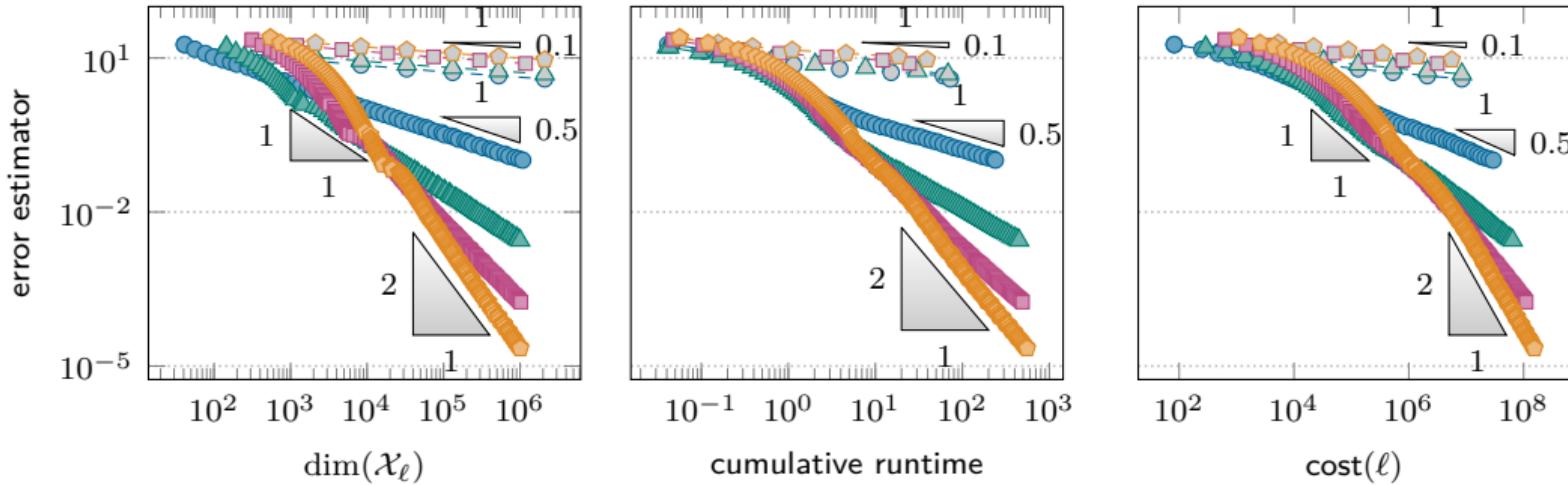
	unif	adap
$p = 1$	- ● -	- ● -
$p = 2$	- ▲ -	- ▲ -
$p = 3$	- ■ -	- ■ -
$p = 4$	- ♦ -	- ♦ -

# How to measure convergence?



	unif	adap
$p = 1$	- ● -	●
$p = 2$	- ▲ -	▲
$p = 3$	- ■ -	■
$p = 4$	- ♦ -	♦

# How to measure convergence?



Linear complexity algorithms ensure

$$\text{cumulative runtime} \approx \sum_{\ell'=0}^{\ell} K[\ell'] \dim(\mathcal{X}_{\ell'}) \approx \sum_{\ell'=0}^{\ell} K[\ell'] \#\mathcal{T}_{\ell'} =: \text{cost}(\ell)$$

	unif	adap
$p = 1$	- ● -	●
$p = 2$	- ▲ -	▲
$p = 3$	- ■ -	■
$p = 4$	- ♦ -	♦

## Stopping criteria for inexact AFEM

- [Becker–Johnson–Rannacher, *Computing*, 1995] algebra error control for MG
- [Chaillou–Suri, *JCAM*, 2007] balancing of error components
- [Arioli–Georgoulis–Loghin, *SISC*, 2013] stopping of algebraic solver in AFEM

## AFEM with optimal complexity

- [Binev–Dahmen–DeVore, *Numer. Math.*, 2004] with coarsening
- [Stevenson, *FoCM*, 2007] for optimal convergence of final iterates
- [Dahmen–Rohwedder–Schneider–Zeiser, *Numer. Math.*, 2008] for eigenvalue problem
- [Becker–Mao, *M2AN*, 2009] for separate marking algorithm
- [Carstensen–Gedicke, *SINUM*, 2012] for eigenvalue problem

**Our main focus:** Parameter-robust convergence

Variational problem	Find $u^* \in \mathcal{X} = H_0^1(\Omega)$ with $b(u^*, v) = F(v)$ for all $v \in \mathcal{X}$
Conforming triangulation	$\mathcal{T}_H$ of bounded polytopal Lipschitz domain $\Omega \subset \mathbb{R}^d$
Discrete subspaces	$\mathcal{X}_H = S_0^p(\mathcal{T}_H) \subset \mathcal{X}$ with fixed polynomial degree $p \in \mathbb{N}$
Discrete problem	Find $u_H^* \in \mathcal{X}_H$ with $b(u_H^*, v_H) = F(v_H)$ f.a. $v_H \in \mathcal{X}_H$
Iterative solver	$u_H^k := \Psi_H(u_H^*; u_H^{k-1})$ with $\Psi_H(u_H^*) : \mathcal{X}_H \rightarrow \mathcal{X}_H$

**Discretization error**  $\eta_H : \mathcal{T}_H \times \mathcal{X}_H \rightarrow \mathbb{R}_{\geq 0}$  for exact discrete solution  $u_H^* \in \mathcal{X}_H$

$$\|u^* - u_H^*\| \lesssim \eta_H(u_H^*) \lesssim \|u^* - u_H^*\| + \text{osc}_H(u_H^*)$$

**Solver error** Contraction  $\|u_H^* - u_H^k\| \leq q \|u_H^* - u_H^{k-1}\|$ ,  $0 < q < 1$  ensures

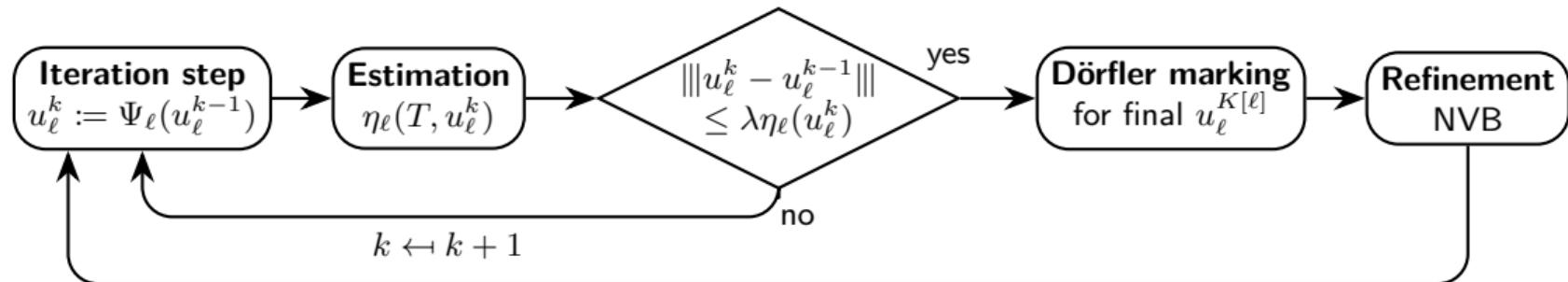
$$\frac{1-q}{q} \|u_H^* - u_H^k\| \leq \|u_H^k - u_H^{k-1}\| \leq (1+q) \|u_H^* - u_H^{k-1}\|$$

**Stability** of the estimator yields

$$|\eta_H(u_H^k) - \eta_H(u_H^*)| \leq C_{\text{stab}} \|u_H^* - u_H^k\|$$

# Adaptive FEM with inexact solvers

**Input:**  $\mathcal{T}_0$ , initial iterate  $u_0^0$ , adaptivity parameter  $0 < \theta \leq 1$ , stopping parameter  $0 < \lambda$



**Output:**  $(\mathcal{T}_\ell)_{\ell \in \mathbb{N}_0}$ ,  $(u_\ell^k)_{(\ell, k) \in \mathcal{Q}}$  ordered by the step counter  $|\ell, k| := \sum_{\ell'=0}^{\ell-1} K[\ell'] + k$

Pfeiler and Praetorius: *Math. Comp.*, 89 (2020)

Stevenson: *Math. Comp.*, 77 (2008)

Define quasi-error  $H_\ell^k := \|u_\ell^\star - u_\ell^k\| + \eta_\ell(u_\ell^k)$

**Theorem** Assume that the estimator  $\eta_\ell$  satisfies **stability**, **reduction**, and **reliability** as well as **(generalized) quasi-orthogonality** of the exact discrete solutions. There exist  $0 < q_{\text{lin}} < 1$  and  $C_{\text{lin}} > 0$  such that for all  $(\ell, k), (\ell', k') \in \mathcal{Q}$  with  $|\ell', k'| < |\ell, k|$  (i.e.,  $u_{\ell'}^{k'}$  was computed earlier than  $u_\ell^k$ )

$$H_\ell^k \leq C_{\text{lin}} q_{\text{lin}}^{|\ell, k| - |\ell', k'|} H_{\ell'}^{k'}$$

This holds without any assumptions on the parameters  $0 < \theta \leq 1$  and  $\lambda > 0$ !

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 Gantner, Haberl, Praetorius and Schimanko: *Math. Comp.*, 90 (2021)

 Feischl: *Math. Comp.*, 91 (2022)

 Bringmann, Feischl, Miraçi, Praetorius and Streitberger: arXiv: 2311.15738 (2023)

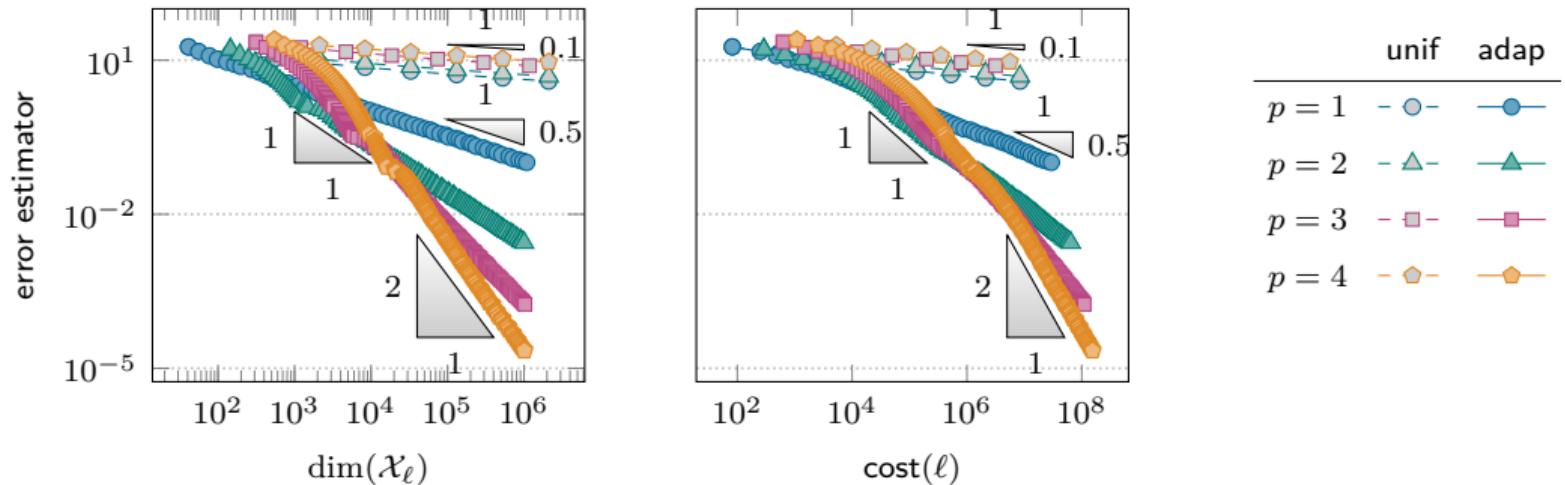
# Corollary – Equivalence of rates and complexity

Assume  $M(s) := \sup_{(\ell,k) \in \mathcal{Q}} (\#\mathcal{T}_\ell)^s \mathsf{H}_\ell^k < \infty$  for some  $s > 0$

$$\begin{aligned} \text{cost}(\ell, k) &:= \sum_{\substack{(\ell',k') \in \mathcal{Q} \\ |\ell',k'| \leq |\ell,k|}} \#\mathcal{T}_{\ell'} \leq M(s)^{1/s} \sum_{\substack{(\ell',k') \in \mathcal{Q} \\ |\ell',k'| \leq |\ell,k|}} (\mathsf{H}_{\ell'}^{k'})^{-1/s} \\ &\leq M(s)^{1/s} C_{\text{lin}}^{1/s} \sum_{\substack{(\ell',k') \in \mathcal{Q} \\ |\ell',k'| \leq |\ell,k|}} (q_{\text{lin}}^s)^{|\ell',k'| - |\ell,k|} (\mathsf{H}_\ell^k)^{-1/s} \\ &\leq \frac{M(s)^{1/s} C_{\text{lin}}^{1/s}}{1 - q_{\text{lin}}^{1/s}} (\mathsf{H}_\ell^k)^{-1/s} \end{aligned}$$

Hence  $M(s) \leq \sup_{(\ell,k) \in \mathcal{Q}} \text{cost}(\ell, k)^s \mathsf{H}_\ell^k \lesssim M(s)$

# Equivalence of rates and complexity



Perturbation argument For  $0 < \lambda < \lambda^*$  sufficiently small

$$(1 - \lambda/\lambda^*) \eta_\ell(u_\ell^K) \leq \eta_\ell(u_\ell^*) \leq (1 + \lambda/\lambda^*) \eta_\ell(u_\ell^K)$$

**Theorem** For  $0 < \theta < \theta^*$  and  $0 < \lambda < \lambda^*$  sufficiently small

$$\begin{aligned} \|u^*\|_{\mathbb{A}_s} &:= \sup_{N \in \mathbb{N}_0} (N+1)^s \min_{\substack{\mathcal{T}_{\text{opt}} \in \text{refine}(\mathcal{T}_0) \\ |\mathcal{T}_{\text{opt}}| - |\mathcal{T}_0| \leq N}} \eta_{\text{opt}}(u_{\text{opt}}^*) \\ &\lesssim \sup_{(\ell, k) \in \mathcal{Q}} \text{cost}(\ell, k)^s \mathsf{H}_\ell^k \lesssim \max \{ \|u^*\|_{\mathbb{A}_s}, \mathsf{H}_0^0 \} \end{aligned}$$

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 Bringmann, Feischl, Miraçi, Praetorius and Streitberger: arXiv: 2311.15738 (2023)

 Bringmann, Miraçi and Praetorius: arXiv: 2404.07126 (2024)

**Strongly monotone** and **Lipschitz continuous** quasi-linear PDE

$$(\mu(|\nabla u|^2)\nabla u, \nabla v)_{L^2(\Omega)} = F(v) \quad \text{for all } v \in \mathcal{X}$$

**Kačanov iteration**  $u_\ell^{k+1,\star} := \Phi_\ell(u_\ell^{k,j})$  defined by

$$(\mu(|\nabla u_\ell^{k,j}|)\nabla \Phi_\ell(u_\ell^{k,j}), \nabla v_\ell)_{L^2(\Omega)} = F(v_\ell) \quad \text{for all } v_\ell \in \mathcal{X}_\ell$$

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-  Haberl, Praetorius, Schimanko and Vohralík: *Numer. Math.*, 147 (2021)
  -  Gantner, Haberl, Praetorius and Schimanko: *Math. Comp.*, 90 (2021)
  -  Becker, Brunner, Innerberger, Melenk and Praetorius: *M2AN*, 57 (2023)
  -  Brunner, Praetorius and Streitberger: (2024)
  -  Miraçi, Praetorius and Streitberger: arXiv: 2401.17778 (2024)

## General second-order linear elliptic problem

$$b(u^*, v) := (\mathbf{A}\nabla u^*, \nabla v)_{L^2(\Omega)} + (\mathbf{b} \cdot \nabla u^* + cu^*, v)_{L^2(\Omega)} = F(v) \quad \text{for all } v \in \mathcal{X}$$

**Zarantonello iteration** Ellipticity and boundedness of  $b(\cdot, \cdot)$  with respect to  $\|\cdot\| = [(\mathbf{A}\nabla \cdot, \nabla \cdot)_{L^2(\Omega)}]^{1/2}$  ensures contraction of  $u_\ell^{k+1,*} := \Phi_\ell(u_\ell^{k,j})$  defined by

$$(\nabla \Phi_\ell(u_\ell^{k,j}), \nabla v_\ell)_{L^2(\Omega)} = (\nabla u_\ell^{k,j}, \nabla v_\ell)_{L^2(\Omega)} + \delta [F(v_\ell) - b(u_\ell^{k,j}, v_\ell)] \quad \text{for all } v_\ell \in \mathcal{X}_\ell$$

for sufficiently small damping parameter  $0 < \delta \leq \delta^*$

**Dual problem** Find  $z^* \in \mathcal{X}$  with  $b(v, z^*) = G(v)$  for all  $v \in \mathcal{X}$

**Goal-error estimate** The discrete goal functional

$$G_H(u_H, z_H) := G(u_H) + [F(z_H) - a(u_H, z_H)]$$

leads to the improved estimate

$$|G(u^*) - G_H(u_H^*, z_H^*)| \leq \|u^* - u_H^*\| \|z^* - z_H^*\| \lesssim \eta_H(u_H^*) \zeta_H(z_H^*)$$

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-  Becker, Gantner, Innerberger and Praetorius: *Numer. Math.*, 153 (2023)
  -  Bringmann, Brunner, Praetorius and Streitberger: *JNUM* (2024)

# Thank you for your attention!

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## Publications & Preprints

P. Bringmann, M. Feischl, A. Miraçi, D. Praetorius and J. Streitberger (2023). *On full linear convergence and optimal complexity of adaptive FEM with inexact solver.* arXiv: 2311.15738

P. Bringmann, A. Miraçi and D. Praetorius (2024). 'Iterative solvers in adaptive FEM'. *Error Control, Adaptive Discretizations, and Applications.* Ed. by F. Chouly, S. P. Bordas, R. Becker and P. Omnes. AAM. Accepted. arXiv: 2404.07126

P. Bringmann, M. Brunner, D. Praetorius and J. Streitberger (2024). *Optimal complexity of goal-oriented adaptive FEM for nonsymmetric linear elliptic PDEs.* JNUM 2024. Accepted for publication. Preprint under arxiv.org:2312.00489



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