

## problem sheet 12

discussion: week of Monday, 17.1.2022

**12.1.** The *secant method* (i.e., Broyden’s method in 1D) to find the zero  $x^*$  of  $F(x) = 0$  is defined as follows given initial points  $x_0, x_1$ :

$$x_{n+1} = x_n - \frac{x_n - x_{n-1}}{F(x_n) - F(x_{n-1})} F(x_n), \quad n = 1, 2, \dots$$

(If  $F(x_n) = F(x_{n-1})$  the difference quotient is formally replaced with  $F'(x_n)$ .) Let  $F(x) = 2 - x^2 - e^x$ .

1. Compute, using Newton’s method the positive zero  $x^*$  of  $F$  to machine precision.
2. Compute the zero  $x^*$  with the secant method. Set  $x_1 = x_0 - \frac{F(x_0)}{F'(x_0)}$ . Plot for  $n \in \{1, \dots, 8\}$  and  $x_0 = 2.5$  the error  $|x^* - x_n|$  versus the step number  $n$ . Also plot the *numerical convergence order*  $p_n = \log(|x^* - x_{n+1}|) / \log(|x^* - x_n|)$  versus  $n$ . What convergence order do you observe?
3. Compare the *efficiency* of the secant method with that of the Newton method by comparing accuracy versus number of function evaluations. To that end, assume that a Newton step costs 3 function evaluations (this is realistic assuming that  $F'$  is approximated with a difference quotient) and plot achieved accuracy versus number of function evaluations. Which method is more efficient?

**12.2.** Show the following convergence result for the inverse iteration with shift: Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be diagonalizable and  $\lambda \in \mathbb{R}$ . Let the eigenvalues of  $\mathbf{A}$  be numbered such that  $|\lambda_1 - \lambda| \geq |\lambda_2 - \lambda| \geq \dots \geq |\lambda_{n-1} - \lambda| > |\lambda_n - \lambda|$ . Then there exists  $C > 0$  such that there holds for the approximations  $\tilde{\lambda}_\ell$  of the inverse iteration:

$$|\lambda_n - \tilde{\lambda}_\ell| \leq C \left| \frac{\lambda_n - \lambda}{\lambda_{n-1} - \lambda} \right|^\ell, \quad \ell = 0, 1, \dots,$$

**12.3.** Consider the vector iteration (“power method”) for the matrix  $\mathbf{A}$  and the following three initial vectors  $\mathbf{x}_0^{(j)}, j = 0, 1, 2$ :

$$\mathbf{A} = \begin{pmatrix} 2 & \\ & -2 \end{pmatrix}, \quad \mathbf{x}_0^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \mathbf{x}_0^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad \mathbf{x}_0^{(3)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Discuss the behavior of the vector iteration. Do the eigenvalue approximations  $\tilde{\lambda}_\ell$  and the iterates  $\mathbf{x}_\ell$  converge? If so, what do they converge to?

**12.4.** Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be a *symmetric* matrix and define the Rayleigh quotient

$$R(\mathbf{x}) := \frac{\mathbf{x}^\top \mathbf{A} \mathbf{x}}{\mathbf{x}^\top \mathbf{x}}$$

- a) Show that the largest eigenvalue  $\lambda_1$  is the maximum of  $R$  and that smallest eigenvalue  $\lambda_n$  the minimum of  $R$ .
- b) The minimization property of  $\lambda_n$  suggests to use descent methods. Formulate such a method. To that end, check that

$$\mathbf{g} := \nabla R(\mathbf{x}) = 2 \frac{\mathbf{A} \mathbf{x} \|\mathbf{x}\|_2^2 - (\mathbf{x}^\top \mathbf{A} \mathbf{x}) \mathbf{x}}{\|\mathbf{x}\|^4}.$$

Use the *Armijo rule* to determine the step length.

*Remark:* in the present case, it is possible to solve the 1-dimensional minimization problem, i.e., finding  $t$  with  $R(\mathbf{x} + t\mathbf{g}) = \min_\tau R(\mathbf{x} + \tau\mathbf{g})$ , explicitly.

- c) Use your algorithm to find the smallest eigenvalue of the tridiagonal matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  given by

$$\mathbf{A} = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & & & \\ -1 & 2 & -1 & & \\ & \ddots & \ddots & \ddots & \\ & & & \ddots & -1 \\ & & & -1 & 2 \end{pmatrix}, \quad h = \frac{1}{n}.$$

Plot (**semilogy**) the error versus the iteration number  $\ell$ , where  $\ell = 1, \dots, 100$ . You may compute the exact value of the eigenvalue using `matlab's eig` command. What do you observe in dependence on  $n \in \{10, 20, 40, 80\}$ ?

*Remark:* As in Problem 11.1 the matrix  $\mathbf{A}$  is obtained as a discretization of  $-\frac{d^2 u}{dx^2}$ .