## Benchmark case: PAC-MAN

## Description

The PAC-MAN geometry is the two-dimensional equivalent to the three-dimensional cat's eye geometry. As shown in Fig. 1, it is a circle of radius  $r_0 = 1$  m with an angular cut-out ranging from  $-\varphi_0$  to  $\varphi_0$  (measured from the x-axis) and  $\varphi_0 = \pi/6$ . An analytical solution of the sound field inside the cut-out and outside the PAC-MAN has been derived [1]. The PAC-MAN problem is suited for radiation and scattering.

Name	PAC-MAN
Field	Linear Acoustics
Code	coded UN2-1 RF or UN2-1 SF
Categories	
Bounded or Unbounded problems	Unbounded
Dimensionality of the case	2D
Scattering or Radiation problem	Scattering and Radiation
Time-domain or Frequency-domain problem	Frequency Domain
Description	
PDE	Helmholtz equation
Geometry	Circle with radius $r_0 = 1$ m. Angular cut-out
	ranging from $-\varphi_0$ to $\varphi_0$ (measured from the
	x-axis), with $\varphi_0 = \pi/6$ . See Fig. 1.
Propagation medium	Air ( $\rho=1.2041~{\rm kg/m^3}$ , $c=343.21~{\rm m/s}$ )
BCs	$Z = \infty$ at boundaries
Sources	Four excitation types. For details see [1].
	1. Surface vibration ( $V_0 = 0.1$ m/s on round surface of the PAC-MAN)
	2. Line source $(r^* = 4m, \varphi^* = \pi/4)$ of unity amplitude
	3. Disk source $(r^* = 4m, \varphi^* = \pi/4, R^* = 0.01m)$ of unity amplitude
	4. Plane wave $(\varphi^* = \pi/4)$ of unity amplitude
Receivers	72 evaluation points located on a circle ( $r = 2m$ ,
	$\Delta \varphi = 5^{\circ},  \varphi_1 = 0^{\circ}, ,  \varphi_{72} = 355^{\circ})$
Quantity to compute	Acoustic pressure of total sound field at
	octave-band center frequencies from 16 Hz to 4 kHz

## References

 H. Ziegelwanger, P. Reiter, The PAC-MAN model: Benchmark case for linear acoustics in computational physics, Journal of Computational Physics 346 (2017) 152–171. doi:10.1016/j.jcp.2017.06.018.

## Geometrical details



Figure 1: The PAC-MAN model consists of a circle (radius  $r_0$ ) with a circular sector of angular width  $2\varphi_0$  cut out. Incident sound field is schematically shown for a cylindrical wave with  $r^* > r_0$  (---), a cylindrical wave with  $r^* < r_0$  (---), and a plane wave (---).  $\mathbf{x}^*$  is the position of a line or a disk source described by its distance  $r^*$  and angle  $\varphi^*$ . v is the velocity of a surface vibration.  $\mathbf{x}$  is the position of an evaluation point.