



APPLICATION master thesis

Provisional working title:

Modeling workplaces in Human-Robot Collaboration: An Interdisciplinary Approach from Engineering, Social Sciences, and HCI

Initial situation / problem:

Task allocation in human-robot collaboration (HRC) determines which agent, human or robot, performs a task based on availability and capability. Optimizing this process enhances productivity. To apply optimization algorithms effectively, workplaces need to be modeled mathematically. This includes representing factors such as task duration, human ergonomics, physical workload, and interaction dynamics in a structured, quantifiable way. Such models enable systematic analysis and optimization of task allocation, efficiency, and human well-being.



The aim of the work:

The objective of this master's thesis is to explore various factors in human-robot collaborative workplaces and investigate how they can be effectively represented in mathematical or computational models. The student **will identify and model key factors** such as task time, ergonomics, and human preferences within a human-robot collaboration setting. These models will then be evaluated to assess their accuracy, relevance, and potential for supporting optimization algorithms

Main tasks:

- Conduct a literature review on human-robot collaboration (HRC) workplaces and relevant modeling approaches
- Analyze and identify key factors influencing HRC settings (e.g., task time, ergonomics, preferences)
- Model the selected factors within a human-robot collaboration scenario
- Evaluate the developed models for accuracy, usability, and potential in optimization contexts

Requirements

- Familiarity with modeling techniques (e.g., mathematical modeling, simulation)
- Programming skills (preferably Python)
- Analytical thinking and interest in interdisciplinary work

You can get more information in a personal conversation with the content supervisor.

First contact / support:	Content support:
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